

## RM\_RotorAssy\_Rev15\_Sm@rtserver\_V19 / PLC\_1 [CPU 1215C DC/DC/DC] / Program blocks / Utilities

### Preload\_Calibration [FB15]

#### Preload\_Calibration Properties

##### General

Name	Preload_Calibration	Number	15	Type	FB	Language	LAD
Numbering	Automatic						

##### Information

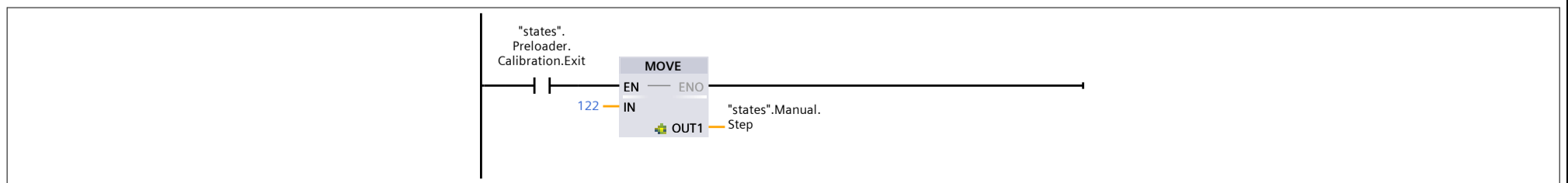
Title		Author		Comment	steps increment by 5 screen increment by 5 starting from 11000	Family	
Version	0.1	User-defined ID					

#### Preload\_Calibration

Name	Data type	Default value	Retain	Accessible from HMI/OPC UA/Web API	Writ-able from HMI/OPC UA/ Web API	Visible in HMI engineering	Setpoint	Supervi-sion	Comment
Input									
Output									
InOut									
▼ Static									
▼ Timers	Struct		Non-retain	True	True	True	False		
▼ sample_time1	IEC_TIMER		Non-retain	True	True	True	True		
PT	Time	T#0ms	Non-retain	True	True	True	False		
ET	Time	T#0ms	Non-retain	True	False	True	False		
IN	Bool	false	Non-retain	True	True	True	False		
Q	Bool	false	Non-retain	True	False	True	False		
▼ sample_time2	IEC_TIMER		Non-retain	True	True	True	True		
PT	Time	T#0ms	Non-retain	True	True	True	False		
ET	Time	T#0ms	Non-retain	True	False	True	False		
IN	Bool	false	Non-retain	True	True	True	False		
Q	Bool	false	Non-retain	True	False	True	False		
▼ MotorWarmup_time3	IEC_TIMER		Non-retain	True	True	True	True		
PT	Time	T#0ms	Non-retain	True	True	True	False		
ET	Time	T#0ms	Non-retain	True	False	True	False		
IN	Bool	false	Non-retain	True	True	True	False		
Q	Bool	false	Non-retain	True	False	True	False		
▼ Sample	Struct		Non-retain	True	True	True	False		
Increment	Int	0	Non-retain	True	True	True	True		
▼ Sample	IEC_COUNTER		Non-retain	True	True	True	False		
CU	Bool	false	Non-retain	True	True	True	False		
CD	Bool	false	Non-retain	True	True	True	False		
R	Bool	false	Non-retain	True	True	True	False		
LD	Bool	false	Non-retain	True	True	True	False		
QU	Bool	false	Non-retain	True	True	True	False		
QD	Bool	false	Non-retain	True	True	True	False		
PV	Int	0	Non-retain	True	True	True	False		
CV	Int	0	Non-retain	True	True	True	False		
Static_1	Bool	false	Non-retain	True	True	True	True		
▼ Average	Struct		Non-retain	True	True	True	False		
▼ Sample	IEC_COUNTER		Non-retain	True	True	True	False		
CU	Bool	false	Non-retain	True	True	True	False		
CD	Bool	false	Non-retain	True	True	True	False		
R	Bool	false	Non-retain	True	True	True	False		
LD	Bool	false	Non-retain	True	True	True	False		
QU	Bool	false	Non-retain	True	True	True	False		
QD	Bool	false	Non-retain	True	True	True	False		
PV	Int	0	Non-retain	True	True	True	False		
CV	Int	0	Non-retain	True	True	True	False		
sum	DInt	0	Non-retain	True	True	True	False		
AVG_Val	Real	0.0	Non-retain	True	True	True	False		
Temp									
Constant									

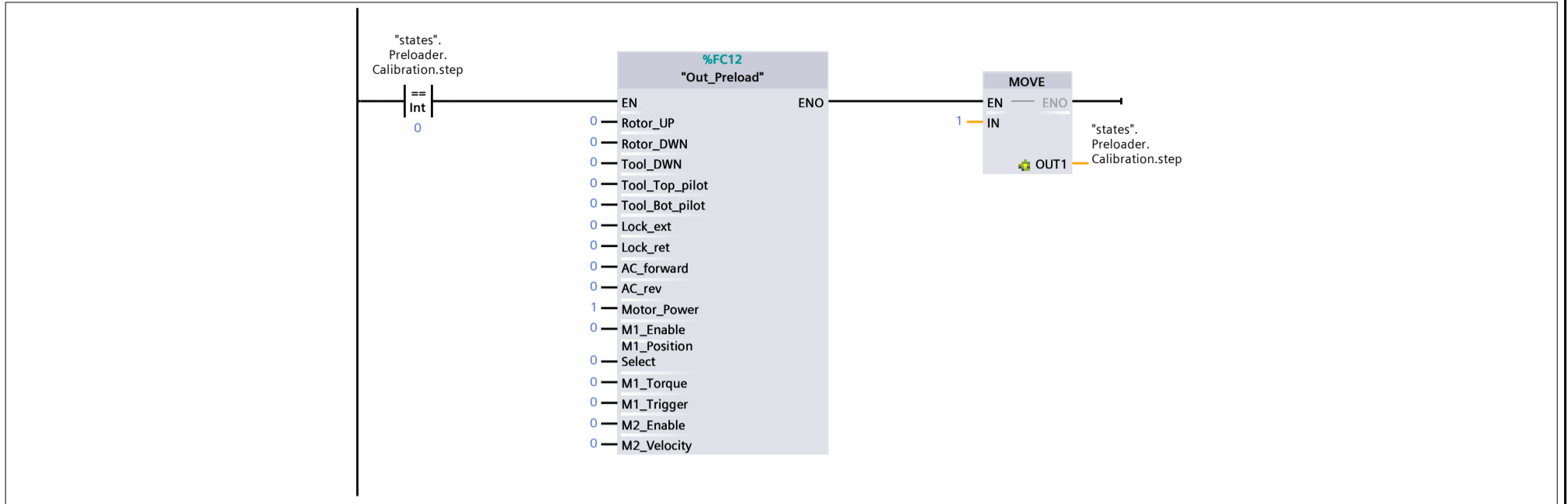
#### Network 1: Exit Calibration & back function

restores former value (Unlike "Confirm" which replaces former value with newly calibrated values)



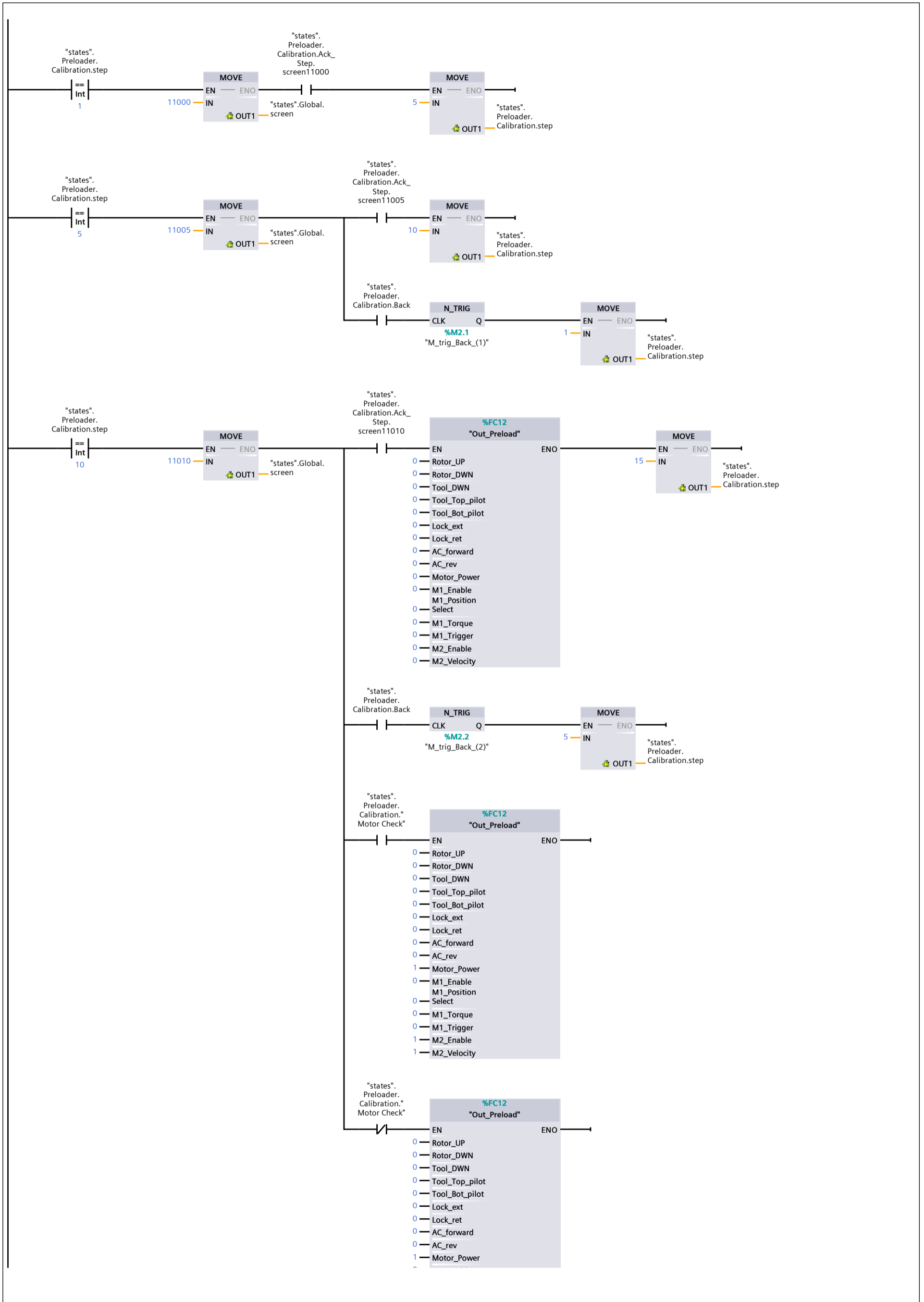
### Network 2: initialization

incase any steps are required before running through the calibration steps



### Network 3: Assemble the sensor jig

Network 3: Assemble the sensor jig (1.1 / 2.1)



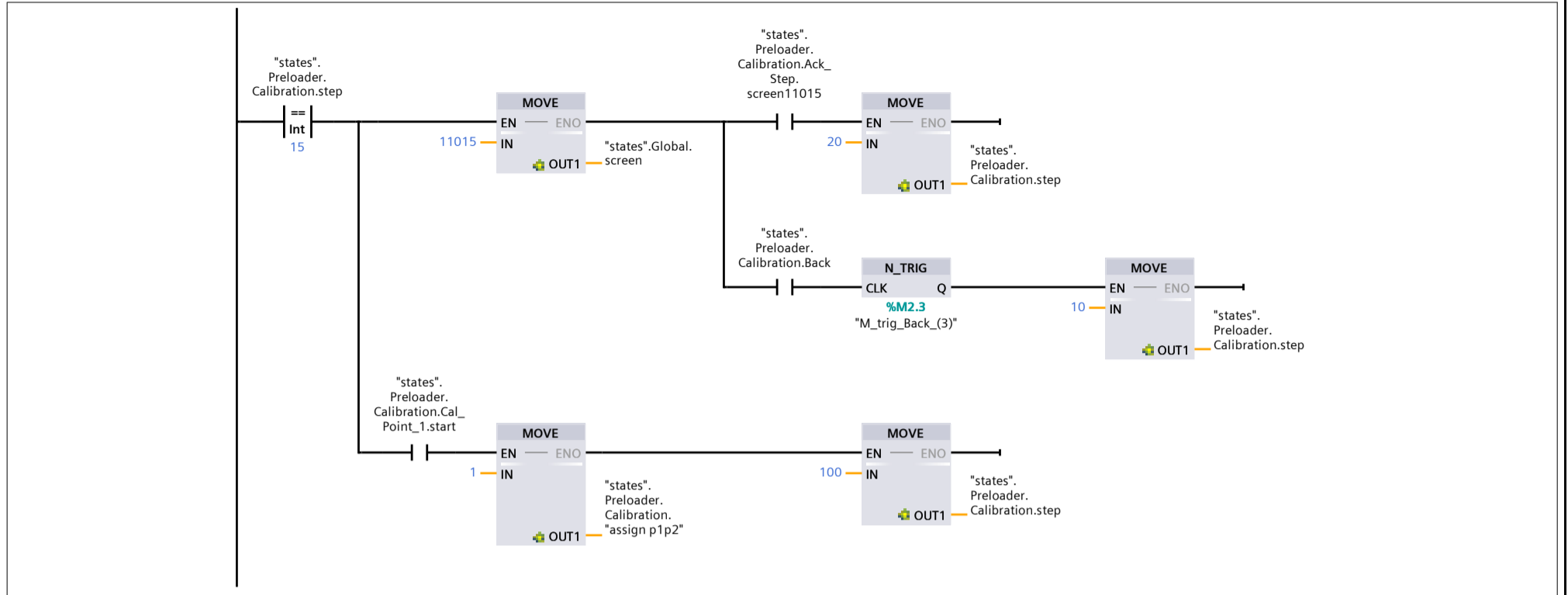
Network 3: Assemble the sensor jig (2.1 / 2.1)

1.1 ( Page1 - 3)

- 0 M1\_Enable
- 0 M1\_Position
- 0 Select
- 0 M1\_Torque
- 0 M1\_Trigger
- 0 M2\_Enable
- 0 M2\_Velocity

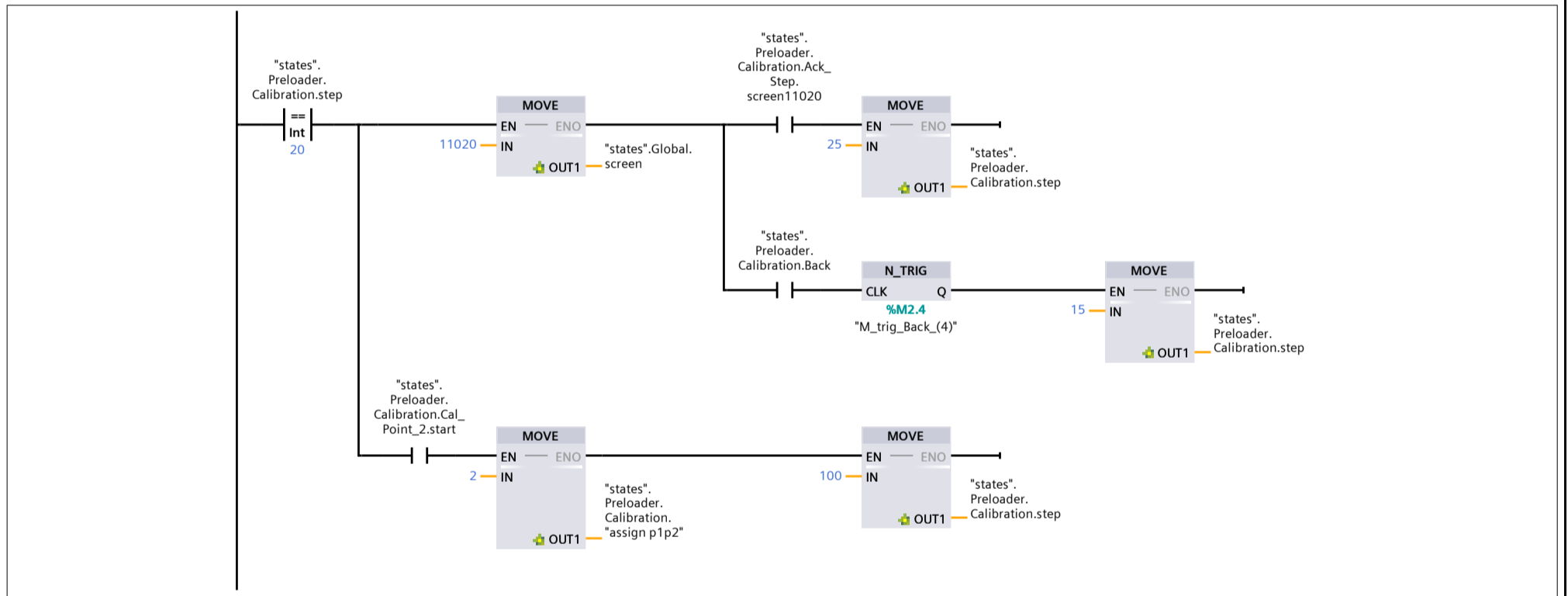
### Network 4: Measure the motor torque at 1st current/voltage

5.5 - 15 ozf-in



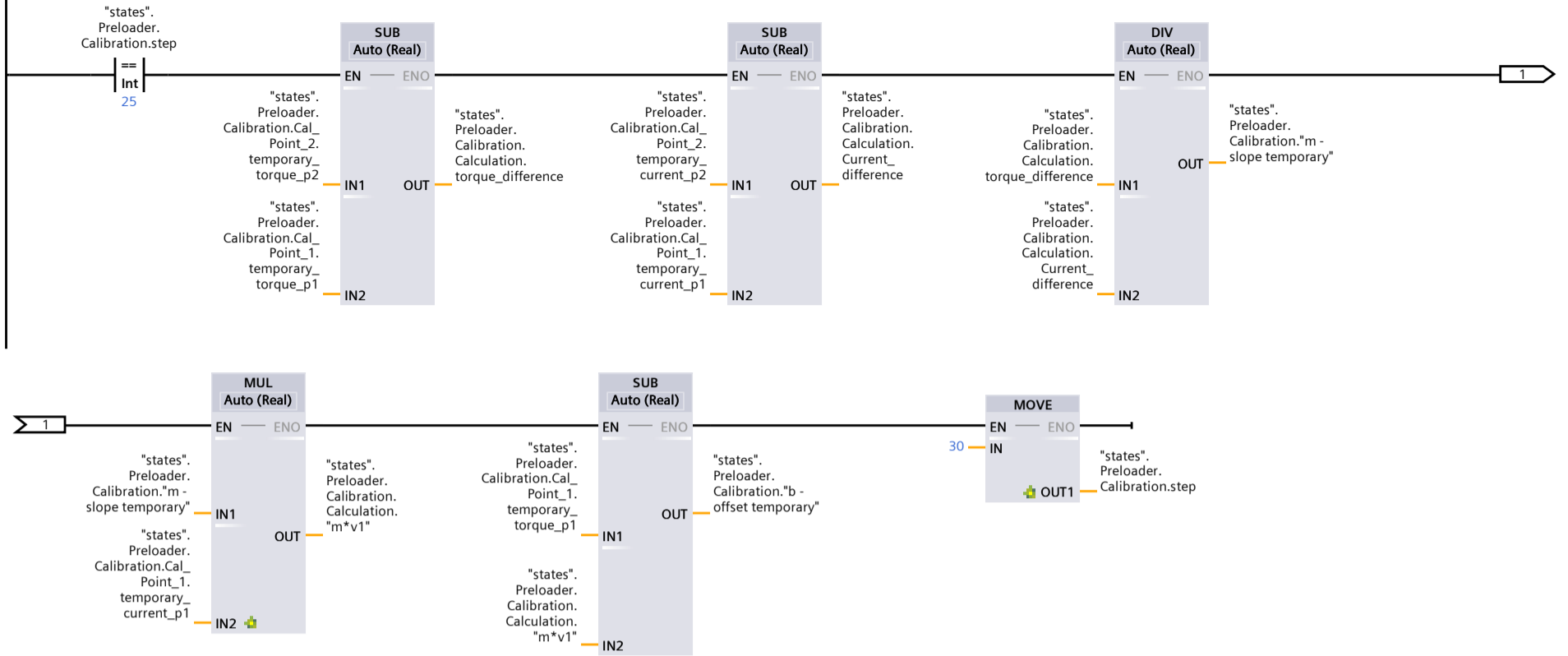
### Network 5: Measure the motor at 2nd interval

5.5 - 15 ozf-in

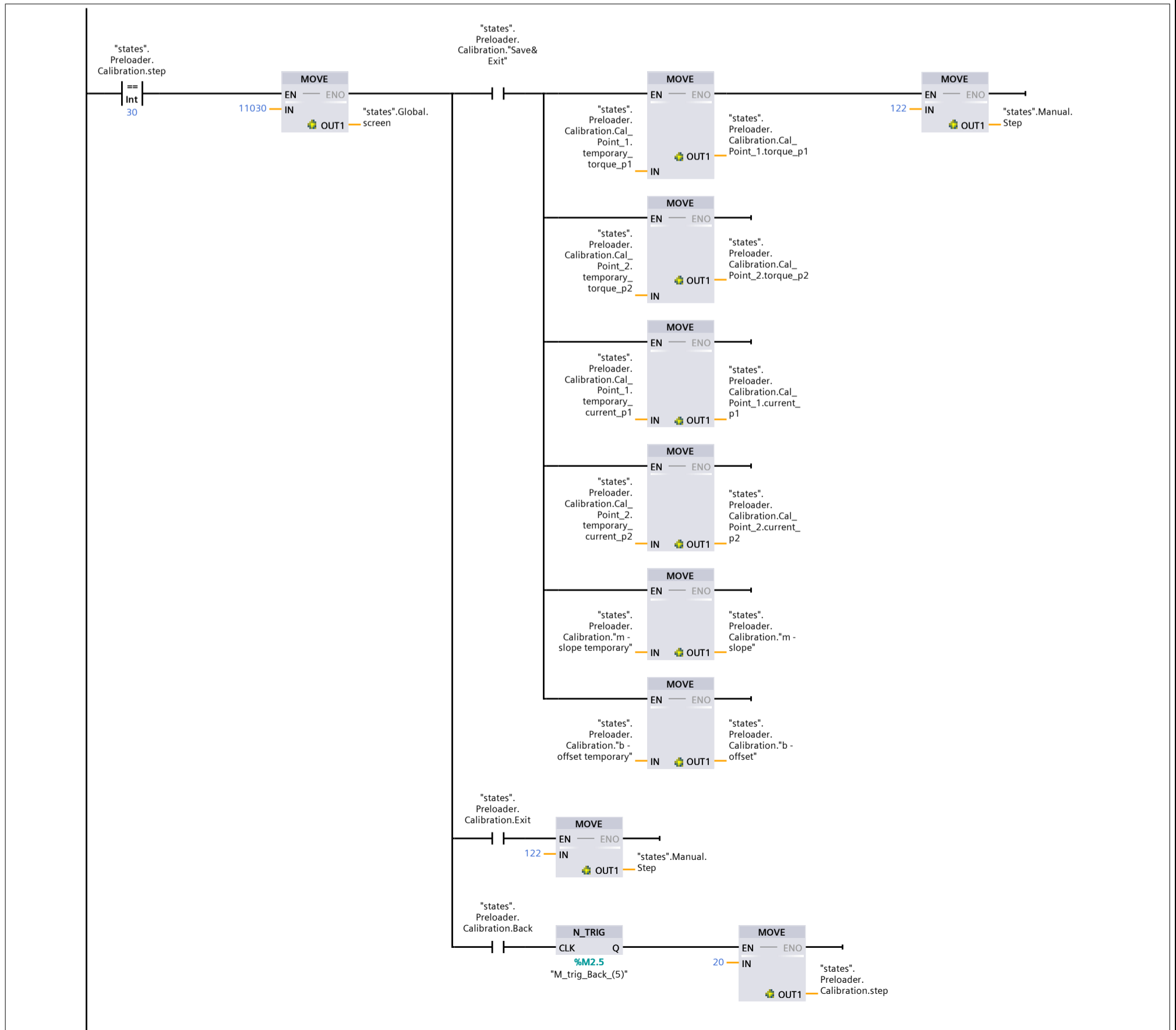


### Network 6: Perform calculation to determine new scale value

find slope (m) and offset (b) in the  $y=mx+b$   
 $slope = (t2-t1)/(v2-v1)$   
 $offset = t1-m*v1$

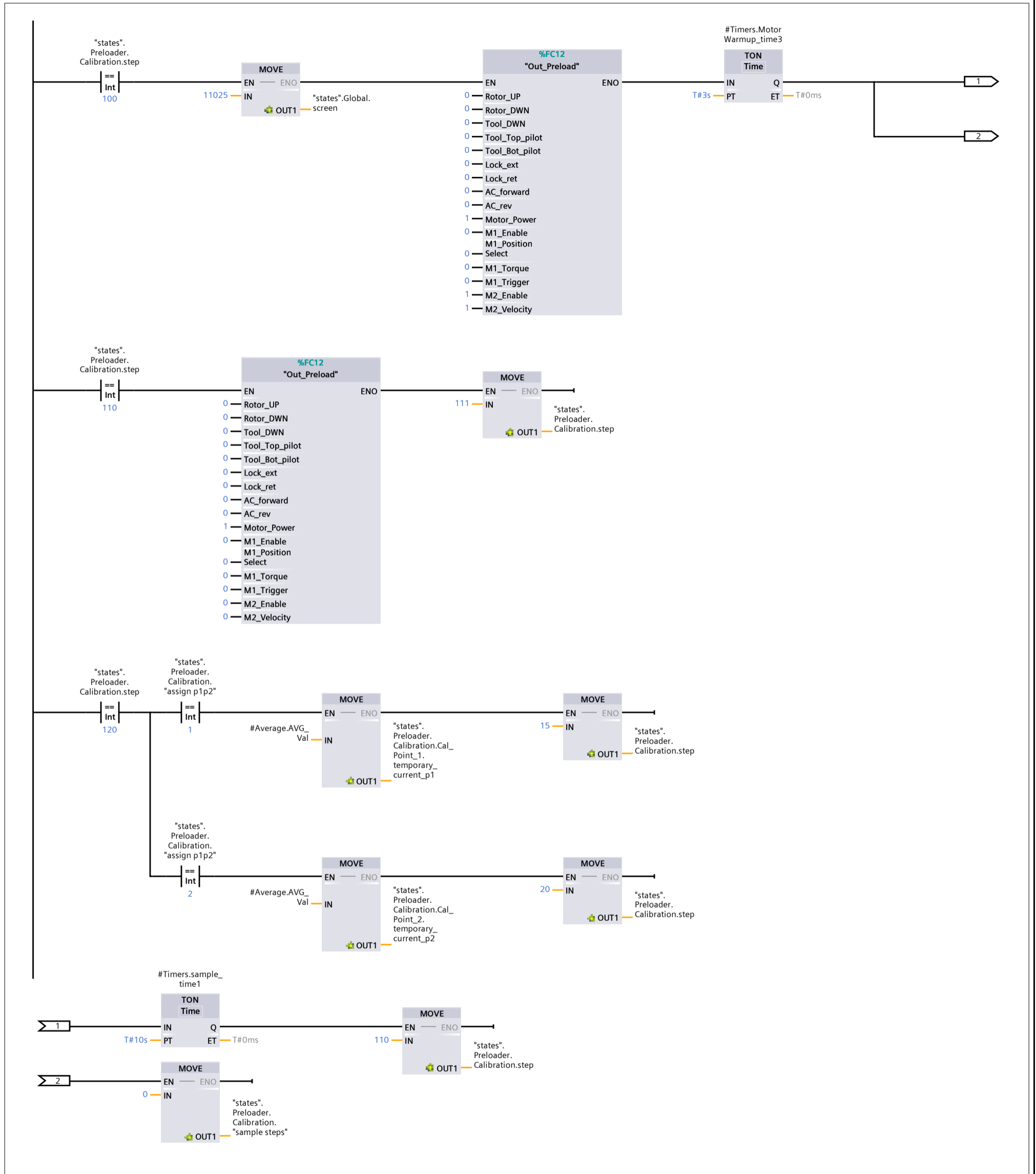


Network 7: Exit Calibration



### Network 8: Motor and current draw for p1 and p2

run the motor for 10 seconds  
 turn off the motor  
 assign the values



### Network 9: sample increments

0 - initialize  
 1 - start of loop, insert into array, add one to increment, wait 6ms, and repeat

